

de Cartagena

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acadēmie Rice

Project: BLUE TEmPLATE BLUE TEch PArTnership Education

MODEL OF

THEORETICAL-PRACTICAL JOB ORIENTATION ACTIVITIES Path Evaluation

METALWORKS, ELECTRONICS, PRECISION ELECTRONICS (M.E.P.)

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THEORETICAL-PRACTICAL JOB ORIENTATION ACTIVITIES Path Evaluation 20__-20__ **METALWORKS, ELECTRONICS, PRECISION ELECTRONICS (M.E.P.)**

| Student: | Class: | School Tutor: | |
|-------------------------------------|-----------------|--------------------------|--|
| Company – Organisation: | | Company Tutor: | |
| Period: fromto _ | | Total Hours: | |
| Role in the activities to carry out | tutored or from | ntal learning activities | |

Role in the activities to carry out: tutored or frontal learning activities

Subjects of Study concerned: Mechatronics, Robotics with elements of Cinematics and Dynamics, Electronics and Precision Electronics, Laboratories

If applicable, evaluate with score 1 to 5 the student's degree of mastery of the following skills (5 = Excellent, 4 = Very Good, 3 = Good, 2 = Sufficient, 1 = Insufficient, X = Not applicable)

| Skills | Level of ability to: | 5 | 4 | 3 | 2 | 1 | > |
|---|-----------------------------------|-----|-----|-----|-----|---|---|
| Evaluation of material resistance | carry out the provided activities | | | | | | |
| | operate autonomously | | | | | | |
| | use of tools and equipment | | | | | | |
| | process and interpret data | | | | | | |
| Development and succession of the processing phases of a mechanical part. | carry out the provided activities | | | | | | |
| | operate autonomously | | | | | | |
| | use of tools and equipment | | | | | | |
| | process and interpret data | | | | | | |
| Programming logic of a CNC machine. | carry out the provided activities | | | | | | |
| | operate autonomously | | | | | | |
| | use of tools and equipment | | | | | | |
| | process and interpret data | | | | | | |
| Design and construction logic of a robot | carry out the provided activities | | | | | | |
| | operate autonomously | | | | | | |
| | use of tools and equipment | | | | | | |
| | process and interpret data | | | | | | |
| | carry out the provided activities | | | | | | |
| Programming logic of a robot and motion mechanics | operate autonomously | | | | | | |
| | use of tools and equipment | | | | | | |
| | process and interpret data | | | | | | |
| Design logics | carry out the provided activities | | | | | | |
| | operate autonomously | | | | | | |
| | use of tools and equipment | | | | | | |
| | process and interpret data | | | | | | |
| Programming logics | carry out the provided activities | | | | | | |
| | operate autonomously | | | | | | |
| | use of tools and equipment | | | | | | |
| | process and interpret data | | | | | | |
| e: School Tutor | | Com | pan | y T | uto | ~ | |

Erasmus+ Programme of the European Union